SECURINGE-VOTINGSYSTEMUSINGBLOCKCHAINBASEDTECHNOLOGY

V.RukeshAnand¹,Dr.S.Kavitha²

¹DeptofComputerScienceandApplications,SchoolofArtsandScience,VinayakaMission'sResearchFoundation, Chennai, India.

Email:rukeshanand46@gmail.com

²AsociateProfessorandHead, DeptofComputerScienceandApplications,SchoolofArtsandScience,VinayakaMission's ResearchFoundation,Chennai,India. Email:kavitha@avit.ac.in

Abstract

As mobile devices develop into powerful and widespread computingdevices, their use is also increasing rapidly. How ever, due to resource constraints and connectivity issues, mobile device users often experience issueswhen running intensive applications on thedevice itself, or when loading them remote cloud. on a Ironically, most users' environments are filled with devices with significant com putational resources. This paper argues that nearby mobile devices can be used crowd-driven cloud efficiently as resource tocomplementremoteclouds. Nodeheterogeneity, unknownworkercapacity, and mobility are identified as essential challenges whenschedulingtasks betweennearbymobile devices. Weintroduceawork-sharing model, called Honeybee, that uses an adaptation of the well-known work theft method to load balancing independent jobsbetween different mobile nodes, which is not limited

randomlydroppingnodesandabletojointhesystem. Honeybee's overalls trateg yistofocusonshort-

termgoals, taking advantage of opportunities, based on the concepts of proactive activists and opportunistic delegates. We evaluate our models and implement two applications using the Prototype framework built using Android. We report speeds of up to 4 with seven devices and up to 71% energy savings with eight devices.

Keywords: Mobile edge-clouds, crowdsourcing, mobile crowdcomputing, offloading

1. INTRODUCTION

Today'senvironmentisbecomingintertwinedwithmobiledeviceswithenh ancedcapabilitiesequippedwithvarioussensors, wireless connectivity as well as limited computational resources. Whether we are on the go, on the train, at the airport, in a shopping center or on the bus, a plethora of mobile devices surround us every day [47], thus creating a resource-saturatedecosystemofmachine and human intelligence. buildup.-Lignans. However, beyond some traditional web-

basedapplications, current technology does not facilitate the exploitation of this resource-rich space of machine and human resources. Collaboration between such smart mobile devices could pave the way for more computing opportunities [54], not only by reducing crowdsource computing opportunities [29] requiring a human element, but also by solving the resource limitation problem inherent in mobile devices. Even by doing The focus of this paper is on the mobile crowd (or edge-cloud). Inourview, the human user of a mobile device is also a resource, which adds an element of crowd computing [48] to the mobile cloud as well. Therefore, we call this particular mobile cloud the mobile crowd. The ereares everal unique features that differentiate a mobile congestion environ ment from a typical grid/distributed computing cluster, such as low computation power and limited energy at nodes, node mobility resulting in frequent disconnects, and node asymmetry [22]. Therefore, the solution cannot be used from grid/distributed computing, and needs to be adapted to the needs of mobile congestion environments.

2. **RELATEDWORK**

AMerwaday, IGuvenc [1]Communicationplaysanimportantrole public during safety operations. Since currentcommunicationtechnologiesrelyheavilyonbackbonenetworks, (BSs) failure of base stations due to natural disastersormaliciousattackscausescommunicationdifficultiesforpublics afetyandemergencycommunications. Recently, theuse of unmanned aerial vehicles (UAVs) such as quadcopters and unmanned gliders has attracted increased attention in publicsafety communications. They can be used as unmanned aerialbase stations (UABS), which can be rapidly deployed as a partof heterogeneous network architecture. However, due theirmobilecharacteristics, interference management innetworks becomes verv challenging. In this paper, we explore the use ofUABS for publics a fety communications during natural disasters, where p artofthecommunicationsinfrastructurebecomesdamaged anddysfunctional(for example,after the2011earthquakeandtsunamiinJapan). Through simulation, we analyze the throughput gain that can be achieved by takingadvantage of the mobility feature of the UAV. Our simulation results suggest that when there is a loss of network infrastructure, deployment of UABs optimized locations at can improve throughput cover a ge and 5 th percentile spectral efficiency ofthe network. In addition, correction with a higherpathlossexponentisconsideredmoresignificant.

A Sendonaris, <u>E Erkip</u>[2] For pt. see i ibid., pp.1927-38. This is the second part of a two-part paper on a new form of spatial diversity, gains where diversity are achieved through collaboration with mobile users. PartIdescribed the user collaborat proposed ion concept and а collaboration strategy foratraditionalcode-divisionmultiple-access(CDMA)system.Part II further examines the collaboration concept and considerspractical implementation. related to its Specifically, issues weexamineoptimalandsub-optimalreceiverdesigns, and the

currentperformanceanalysisforthetraditionalCDMAimplementations proposed in Part I. easy. We show that, underallscenariosstudied,cooperationisbeneficialintermsofincreasings ystemthroughputandcellcoverage,aswellasdecreasing sensitivity tochannelvariations.

E. Erkip; **B.** Aazhang[3] Mobileusers' datarates and quality of service are limited by the fact that, within the duration of any given call, they experience severe changes insignal attenuation, necessitating the use of some sort of variety. In this two-partpaper, we propose anew form of spatial diversity, in which diversity gain sare achieved through collaboration with mobile users. PartIdescribes the user collaboration strategy, while PartII (see ibid., p. 1939-

48) focuses on implementation is sues and performance analysis. The results show that, even though the interuser channel is noisy, collaboration leads not only to increased efficiencies for both users, but also to amore robust system, where users' achievable rates are lower for channel variations. are sensitive.

Zeng, RZhang, TJLim [4]Wirelesscommunication systems that include unmanned aerial vehiclespromisetoprovidecosteffective wire less connectivity for devices without infrastructure coverage.Basedonterrestrialcommunicationsorhigh-altitudeplatforms,ondemandwireless systems with low-altitude UAVs are generally faster todeploy, more flexibly reconfigured, and more flexible than thepresence of a short-range line. The reason is likely to be bettercommunication channels. -of-sight links. However, the use of highly mobile and energy-constrained UAVs for wireless communication challenges. also introduces many new In thisarticle, we provide an overview of UAV-

assisted wireless communication by introducing the basic networking archit ecture and key channel characteristics, highlighting keydesign considerations as well as new opportunities for exploitation.

3. EXISTINGSYSTEM

Cloud computing is efficient and scalable but maintaining thestabilitytoprocesssomanyjobsinacloudcomputingenvironment is a very complex problem, with load balancingattracts a lot of attention to researchers. Since the job arrivalpattern is not predictable and the capacity of each node in thecloud varies, for load balancing issue, workload control is there. It is important to improve system performance and maintainstability. Load balancing schemes canbe staticor

dynamic, dependingonwhether the dynamics of the systemare important. Static plans do not use system information and areless complex whereas dynamic plans will incur additional coststothe system but may change as the state of the system changes. Adynamic scheme is used here for its flexibility.

Disadvantage

- Load balancing schemes can be either static ordynamic depending on whether the dynamics of thesystem isimportant.
- Staticschemesdonotusesystem information andarelesscomplex.

• Dynamicplan isusedforthisflexibility.

4. **PROPOSEDWORK**

Loadbalancingschemes canbe static or dynamic, dependingon whether dynamics system of the are important. the Staticplansdonotusesysteminformationandarelesscomplexwhereas dynamic plans will incur additional costs to the systembut may change as the state of the system changes. A dynamic scheme is used here for its flexibility. The model consists of amain controller and balancer to collect and analyze information. Thus, dynamic control has little effect on other worknodes. The state of the system then provides a basis for choosing theright load balancing strategy. The proposed method will displaythe area wise pollution rate. Things like automobiles, fertilizers, pesticides, energy production (such coal). and as agricultural production contribute pollutants to the surroundingair. Topogr aphy can amplify the effects of pollutants, trap theminside a confined area or make it easier for pollutants to settlerather thanbe carriedbythewind.



5. ARCHITECTURE

The Structural design of the proposed system is shown in the figure-1:



Fig1:SourcelocationprivacyprotectionArchitecture

6. MODULEDESCRIPTION

6.1 System Model

There are several cloud computingcategories with this task focused on the public cloud. Apublic cloud is based on the

standard cloud computing model with the service provided bytheserviceprovider. Alarge public cloud will consist of multiple nodes and nodes in different geographic locations. Acloudpartitionisusedtomanagethislargecloud.Cloudsegmentation is a subregion of the public cloud that consists of divisions based on geographic locations. Deciding with the main controller which cloud partition should get the job done. The partition load balancer then decides how to assign tasks to he nodes. When the load state of the cloud partition is normal, this partition can be completed locally. If the cloud partitionloadconditionisnotnormal, this task should be movedtoanotherpartition.

6.2 Maincontrollerand balancers

Theloadbalancingsolutionisdonebythemaincontrollers and balancers. The main controller first delegatestasks to the appropriate cloud partitions and then communicates with the balancers in each partition to refresh this status infor controller deals mation. Since the main with informationforeachpartition, smaller datasets will lead to higher processin grates.Ineachpartitionthebalancerscollectthestatus information from each node and then choose the rightstrategy todistribute the jobs.

6.3 Assigningjobstothecloudpartition

Whenajobhitsthepubliccloud,thefirststepischoosingtherightpa rtition.Cloudpartitionstatuscanbedivided intothree types:

IIdle:WhenthepercentageofinactivenodesexceedsbalancerA,switcht oinactive state.

ii. Normal:WhenthepercentageofcommonnodesexceedsBalancerB, switchestothe normalloadstate.

iii. Overload:Whenthepercentageofoverloadednodesexceedsbalan cer C,switchestooverloaded state..

6.4 Motivation

Arelativelysimplemethodcanbeusedforthesplitpassive state method complex with more for the normalstate.Loadbalancersswitchmethodsasthesituationchanges . Here, the idle position uses an improved roundrobin algorithm position while the normal uses а gametheorybasedloadbalancing strategy.

6.5 Loadbalance strategyforthe idlestatus

There are many simple load balancing algorithm methods likerandomalgorithm, weightroundrobinanddynamicroundrobin. For its simplicity the round robin algorithm is used here. The round robin algorithm is one of the simplest load balancingalgorithms, which forwards each new request to the next serverin the queue. The algorithm does not record the status of each connection, so it has no status information. In regular roundrobinalgorithm, each node has an equal chance of being selected. However. in the public cloud, the configuration andperformanceofeachnodewillnotbethesame; Thus, thismethodmayoverloadsomenodes. Thus, an improved round

robinalgorithmisused,called"roundrobinbasedonloaddegree evaluation". The algorithm is still quite simple. Beforethe round robin phase, the nodes in the load balancing table aresorted byload degree from lowesttohighest.

6.6 Loadbalancingstrategy for the normalstatus

When cloud segmentation is normal, jobs are arriving muchfasterthanintheidlestateandthesituationisfarmorecomplex,soadiffe rentstrategyisusedforloadbalancing.Everyuserwantshistasktobecomplet edintheshortestpossibletime,sothepublic cloudneeds amethodthat cancomplete all the users' tasks with a reasonable response time. Astaticloadbalancingstrategybasedongametheorywasproposed for distributed systems. And this work gives us a newreview of the load balancing problem in a cloud environment.As a distributed system implementation, load balancing in acloud computingenvironmentcanbeviewedasa game.

7. RESULTS



Fig2:Mobilestation.



Fig 3 : Mobilestation B



Fig4 :MobilestationC.



Fig7 : MobileStation BReceivedfiles



Fig 5:Network Comparison.



Fig8:MobileStation Cfileupload



Fig9:Wimaxnetwork



Fig 6 : MobileStation fileAUploaded

on B

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SENDER MS A MS A MS A MS A MS A MS A	RECEIVER MS B MS B MS B MS B MS B	CARE OF ADDRESS CSN BASN B-BS BAIS B CSN BASN B-BS BAIS B CSN BASN B-BS BAIS B CSN BASN B-BS BAIS B CSN BASN B-BS BAIS B	888	SENDER MS C MS C MS C MS C MS C MS C	RECEIVER MS B MS B MS B MS B MS B MS B	RECEIVER EXISTING PATH CSN BASIN BUBS CAIS B CSN BASIN BUBS CAIS B CSN BASIN BUBS CAIS B CSN BASIN BUBS CAIS B CSN BASIN BUBS BASIS B CSN BASIN BUBS BASIS B	
ι		⊾ Graphical		Gancel	,		Actual Workers

Fig10:NetworkMonitoring

8. CONCLUSION

Wepresentthefollowingconclusions.First, anautonomouslocalmobiled evice is aviable waytoget speed and save energy, sharing work among the crowd. Adding new resources up to an optimal amount can result in increased speed and power savings. Secondly, a generalized framework can

beusedtoabstractmethodsandenableparameterizationforawide variety of tasks made up of independent jobs. Third, theinherentchallengesofmobilecomputingsuchasrandomdisconnections, nopriorinformationonparticipatingnodes, and frequent fluctuations in reso urceavailability can be successfully accommodated through fault to lerance methods and workevasion mechanisms.

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