

Real – Time Emergency Vehicles Recognition For Smart Traffic Management Using Deep CNN

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Abstract -- Real -time emergency vehicle recognition is a vital component of smart traffic management systems aimed at minimizing delays during critical response situations. Rapid urban growth and increasing traffic congestion often obstruct the movement of ambulances, fire engines and police vehicles, leading to serious consequences. To overcome this challenge, this study proposes a Deep Convolutional Neural Network (Deep CNN) -based approach for accurate detection of emergency vehicle from live traffic streams. The system uses advanced computer vision techniques to automatically extract important spatial and visual features from surveillance footage. The proposed Deep CNN architecture consists of multiple convolutional, activation, and pooling layers that learn hierarchical feature representation, followed by fully connected layers for classification. The model is trained on a large, annotated dataset containing images of emergency and non-emergency vehicles under diverse lighting and weather conditions. Data augmentation methods such as rotation, scaling, and brightness variation are applied to enhance robustness and generalization capability.

I. INTRODUCTION

Traffic congestion in rapidly growing urban areas has become a serious challenge for modern transportation systems. One of the most critical issues within congested road network is ensuring uninterrupted passage for emergency vehicles such as ambulances, fire trucks, and police vehicles. Even a small delay in emergency response can lead to severe consequences, including loss of life and property. Therefore, intelligent and automated traffic management solutions are essential. Conventional traffic control systems generally operate on fixed signal timings or

basic sensor mechanisms. These systems are not capable of accurately identifying emergency vehicles in real time, especially under complex traffic, varying illumination, and environmental conditions. Manual intervention or siren-based detection methods are often unreliable and inefficient. Recent advancements in deep learning, particularly Deep Convolutional Neural Networks (CNNs), have significantly improved the performance of computer vision systems in object detection and classification tasks. CNN models are capable of automatically extracting spatial and hierarchical features from images, making them highly effective for recognizing vehicles in dynamic traffic scenes. Real-time detection models such as You Only Look Once and Faster R-CNN demonstrate the feasibility of deploying deep learning for intelligent traffic applications. This project proposes a Real-Time Emergency Vehicle Recognition System for Smart Traffic Management using Deep CNN. The system analyzes live video streams captured from traffic surveillance cameras, detects and classifies emergency vehicles with high accuracy, and enables priority-based traffic signal control. By integrating computer vision and intelligent signal management, the proposed solution aims to reduce emergency response time, improve road safety, and support the development of smart city transportation infrastructure.

II. BACKGROUND AND MOTIVATION

A. Growth of Urban Traffic Congestion

Rapid urbanization and increasing vehicle ownership have significantly increased traffic density in metropolitan cities. In countries like India, expanding urban populations and infrastructure limitations have intensified road congestion. As traffic volume grows, managing intersections efficiently becomes increasingly complex, especially during peak hours. Congestion not only waste fuel and time but also directly affects emergency response systems.

B. Importance of Emergency Vehicle Priority

Emergency vehicles such as ambulances, fire trucks, and police vehicle require immediate right-of-way. Studies consistency show that response time plays a critical role in survival rates during medical emergencies and disaster situations.

Even minor delays caused by traffic signals or blocked intersections can:

- Increase mortality risk in critical patients
- Delay law enforcement response
- Worse fire Damage

Therefore, intelligent priority-based traffic control is not optional – it is essential.

C. Limitation of Traditional Traffic Management Systems

Existing traffic systems typically rely on:

- Fixed-time signal control
- Manual traffic monitoring
- Basic sensor-based detection
- Siren-based recognition.

These approaches have several limitations:

- Inability to accurately identify emergency vehicle in complex traffic
- Poor performance under noisy environments
- Lack of scalability
- Delayed manual intervention

Artificial Neural Network (ANN)- based models used in earlier systems often struggle with feature extraction depth and real-time performance compared to deeper architectures.

D. Advancement in Deep Learning and Computer vision

Recent developments in Deep Convolutional Neural Network (CNNs) have revolutionized image processing and object detection. Architectures such as You Only Look Once and Faster R-CNN demonstrate high accuracy and real-time detection capability in complex visual environments.

CNNs automatically learn hierarchical features such as edges , textures, shapes, and patterns, making them highly suitable for:

- Vehicle detection
- Object localization
- Real-time video analysis

These advancements provide the technological foundation for intelligent traffic management.

E. Motivation for the Proposed System

The primary motivation behind this project is to:

- Reduce emergency response time
- Improve road safety and traffic efficiency
- Automate emergency vehicle detection
- Enable intelligent traffic signal prioritization
- Contribute to smart city infrastructure

By leveraging Deep CNN models, the system aims to overcome the limitations of traditional methods and provide a scalable, accurate, and real-time emergency vehicle recognition framework.

III. NOVEL APPLICATIONS OF EMERGENCY VEHICLES RECOGNITION FOR SMART TRAFFIC MANAGEMENT SYSTEM USING DEEP CNN

The proposed System introduces a novel AI-driven application that integrates real-time deep convolutional neural network (CNN)-based emergency vehicle recognition with adaptive traffic signal control to create an intelligent priority management framework. Unlike traditional traffic systems that rely on fixed timers or manual intervention, this solution enables automatic identification, classification, and localization of ambulances, fire trucks, and police vehicles directly from live traffic video streams.

The novelty lies in combining real-time computer vision with decision-based signal preemption in a unified architecture. By leveraging advanced deep learning models inspired by real-time detection frameworks such as You Only Look Once and region-based detection approaches like Faster R-CNN, the system achieves high detection accuracy under dynamic lighting and dense traffic conditions. The application not only detects emergency vehicles but also evaluates confidence scores and vehicle type to determine priority levels before dynamically adjusting signal timing.

Another innovative aspect is its adaptability to heterogeneous traffic environments, particularly in developing regions where mixed traffic conditions and inconsistent lane discipline present additional challenges. The system can be integrated with existing CCTV infrastructure, reducing the need for heavy hardware modification while supporting scalability across multiple intersections. Overall, this application transforms conventional traffic control into a proactive, AI-powered emergency response mechanism, contributing to reduced response time, enhanced public safety, and the advancement of smart transportation.

ecosystems.

IV.ROLE AND POTENTIAL OF EMERGENCY VEHICLES RECOGNITION USING DEEP CNN

Role:

The proposed system plays a transformative role in modern intelligent transportation systems by integrating deep learning-based computer vision with adaptive traffic signal control. It shifts management from a static, time-based approach to a dynamic, AI-driven decision-making framework.

A. Role in Intelligent Traffic Automation – Traditional traffic systems operate on predefined signal timings without contextual awareness. This project introduces real-time visual intelligence into intersections. By continuously analyzing live traffic video streams, the system automatically identifies emergency vehicles and triggers appropriate signal preemption mechanisms. This reduces human intervention and ensures faster, unbiased, and consistent decision-making.

B. Role in Emergency Response Enhancement – Time is the most critical factors in emergency services. A delay of even a few minutes can significantly affect patient survival rates or damage control in fire emergency. The system ensures:

- Immediate detection of ambulances, fire trucks, and police vehicles
- Automatic traffic signal clearance
- Reduced wait time at intersections
- Faster access to destination points

Thus, it directly contributes to life- saving operations.

C. Role in Smart City Infrastructure – Modern smart cities rely on data-driven systems for urban management. The proposed framework can be integrated into centralized traffic monitoring centers, enabling:

- Real-time emergency tracking
- Signal override monitoring
- Automated reporting
- Performance analytics.

This makes the system compatible with next-generation urban planning initiatives.

D. Role in AI-Based Decision Systems – The project demonstrates the practical application of Deep Convolutional Neural Networks in real-world infrastructure. Inspired by real-time

object detection frameworks such as You Only Look Once, the system performs:

- Feature extraction
- Object localization
- Multi-class classification
- Confidence-based prioritization

It serves as a model for how deep learning can move beyond theoretical research into real-time societal applications.

E. Role in Reducing Traffic Congestion Impact – By dynamically adjusting signal timing when necessary, the system ensures that emergency priority does not permanently disrupt traffic flow. Instead, it temporarily optimizes signals and then restores normal operation, maintaining overall traffic balance.

Potential:

The potential of this project extends significantly beyond its current implementation and opens multiple avenues for research, development, and technological expansion.

A. Scale Deployment Potential – The system can be scaled across multiple intersections within a city. Since it can utilize existing CCTV infrastructure, deployment costs remain relatively manageable compared to infrastructure-heavy alternatives. It has the potential to become a standard module in intelligent traffic systems.

B. Integration with IoT and Smart Sensors – The framework can be enhanced by integrating IoT-based traffic sensors, GPS-enabled ambulances, and vehicle-to-infrastructure (V2I) communication systems. This would create a hybrid verification mechanism combining visual detection with digital authentication.

C. Predictive Route Optimization – Future extension can include route prediction algorithms. By tracking the movement direction and speed of emergency vehicles, the system could proactively adjust multiple signals along the predicted path, forming an automated green corridor.

D. Expansion to Multi-Hazard Detection – The model can be extended to detect:

- Road accidents
- Traffic violations
- Over-speeding vehicles
- Congestion levels

This transforms the project from a single-purpose system into a comprehensive traffic intelligence platform.

E. Data Analytics and Policy Making – The collected data can support:

- Peak emergency movement analysis
- High-delay intersection identification
- Average signal clearance time evaluation
- Urban infrastructure improvement planning
- Authorities can use these insight for long-terms traffic policy optimization

F. Research and Academic Potential – The project opens opportunities for:

- Improving CNN architectures
- Comparing detection models
- Implementing edge computing
- Integrating reinforcement learning for adaptive signal control
- It provides a strong foundation for further postgraduate or research-level

G. Social and Economic Impact Potential – Reduced emergency delays can:

- Save lives
- Minimize property damage
- Reduce fuel wastage
- Lower traffic congestion stress

This demonstrates both technological and societal value

V. INNOVATIVE INTEGRATION OF DEEP LEARNING IN EMERGENCY VEHICLES RECOGNITION

The proposed system represents an innovative convergence of artificial intelligence, computer vision, embedded control systems, and intelligent transportation infrastructure. Rather than implementing emergency vehicle detection as a standalone vision task, the project integrates detection, decision-making, and physical traffic control into a unified intelligent ecosystem.

- A. End-to-End AI-Infrastructure Integration – A major innovation of this project lies in its end-to-end pipeline architecture. The system does not stop at identifying emergency vehicles; instead, it connects detection results directly to real-time traffic signal control mechanisms.

The integrated workflow includes:

- Live video acquisition from surveillance cameras
- Frame preprocessing and normalization
- Deep CNN-based feature extraction and classification
- Confidence evaluation and priority decision logic
- Automated signal preemption and restoration

This seamless interaction between perception (AI model) and action (traffic signal control) transforms passive monitoring into active traffic management.

- B. Real-Time Deep Learning Embedded in Physical Systems – Deep learning models are often used in research environments or offline processing systems. This project innovatively embeds a Deep Convolutional Neural Network into a real-time operational infrastructure.

Inspired by efficient object detection architectures such as You Only Look Once, the system ensures:

- Low latency detection
- Multi-class vehicle classification
- Accurate localization in dynamic traffic scenes
- Continuous frame-by-frame monitoring

The integration of high-level AI perception into time-sensitive signal control makes the system practically deployable rather than purely theoretical.

C. Multi-Layer Modular Architecture – The project introduces a modular architecture that enhances flexibility and scalability. Each module performs a specialized function while remaining interconnected:

- Vision & Preprocessing Layer – Captures raw traffic video, performs resizing, normalization, and noise reduction to improve model robustness under varying lighting conditions.
- Deep CNN Detection Layer – Learns hierarchical spatial features such as vehicle shape, emergency markings, and structural patterns for accurate classification.
- Intelligent Decision Layer – Implements confidence-based thresholding and rule-based prioritization logic to prevent false signal triggers.
- Signal Control & Monitoring Layer - Interfaces with traffic controllers to dynamically adjust signal timing and restore normal cycles after emergency passage.

This layered integration ensures system reliability and simplifies future expansion.

D. Context-Aware Model Customization – Unlike generic object detection systems, this project integrates region-specific adaptation. By training the CNN on Indian emergency vehicle datasets, the model accounts for:

- Variations in ambulance color schemes
- Diverse vehicle body structures
- Mixed traffic conditions
- Inconsistent lane discipline

This contextual adaptation increases detection accuracy in real-world heterogeneous environments.

E. Hybrid Intelligence Possibility – The integrated framework is designed to support hybrid intelligence models. The system can be expanded to combine:

- Visual CNN detection
- Acoustic siren pattern recognition

- GPS-based verification
- IoT-based vehicle authentication

This multi-modal integration would significantly reduce false positives and improve reliability.

F. Scalability Through Edge and cloud Integration – The architecture allows flexible deployment models:

- Edge deployment for low-latency intersection-level processing
- Cloud integration for centralized monitoring and analytics
- Hybrid models for distributed intelligence

This makes the system adaptable for both small-scale and city-wide implementation.

G. Data -Driven Feedback Loop Integration – The project not only detects emergencies but also enables continuous system improvement. Detection logs and signal preemption data can be analyzed to:

- Measure average clearance time
- Identify high-delay intersections
- Optimize future signal timing policies
- Improve model retraining cycles

This creates a self-improving AI-enabled traffic ecosystem.

H. Integration with Future Smart Transportation Systems – The framework is compatible with advanced transportation technologies, including:

- Vehicle-to-Infrastructure (V2I) communication
- Connected and Autonomous Vehicle (CAV) environments
- Reinforcement learning–based adaptive traffic systems
- Smart city centralized control dashboards

Thus, the system is not a standalone solution but a foundational module

for next-generation intelligent mobility systems.

VI. RECENT ADVANCEMENT IN DEEP LEARNING AND HUMAN SENTIMENT ANALYSIS

Multimodal and Real-Time Emergency Vehicle Recognition – Recent advancements in deep learning have significantly enhanced emergency vehicle recognition systems by integrating multiple data sources such as visual feeds, acoustic siren signals, and traffic sensor data for more accurate detection. Modern AI-powered models now utilize advanced Convolutional Neural Networks (CNNs) and transformer-based object detection architectures to identify ambulances, fire trucks, and police vehicles in complex urban environments. These systems analyze vehicle shape, flashing light patterns, and motion characteristics while simultaneously processing siren audio signals to improve reliability. Real-time adaptive learning enables models to update detection strategies dynamically, ensuring consistent performance under varying lighting conditions, heavy traffic congestion, and adverse weather scenarios. This multimodal approach strengthens smart traffic management systems by enabling automatic traffic signal prioritization, reducing emergency response times, and improving public safety infrastructure.

Edge Deployment and Intelligent Traffic Integration – With the development of lightweight and optimized deep learning architectures, emergency vehicle recognition models can now be deployed on embedded and edge computing platforms for low-latency processing. Real-time inference on surveillance cameras and intelligent traffic control units allows immediate communication between detection systems and adaptive traffic lights. This integration ensures that traffic signals automatically switch to green when an emergency vehicle is detected, minimizing delays at intersections. Additionally, advancements in transfer learning and synthetic data augmentation improve model accuracy even with limited labeled emergency vehicle datasets. These improvements make the system scalable for smart cities, autonomous vehicles, and intelligent transportation networks, ensuring seamless coordination between AI detection modules and urban mobility systems.

Fairness, Explainability, and Future Directions – As emergency vehicle recognition systems become part of critical infrastructure, recent research

emphasizes fairness, transparency, and privacy-preserving AI deployment. Explainable AI (XAI) techniques, such as attention heatmaps and feature visualization, help interpret model decisions, ensuring reliability in safety-critical applications. Privacy-aware learning methods reduce risks associated with continuous surveillance data processing, while bias mitigation strategies ensure consistent detection across diverse environments and vehicle types. Future advancements are expected to focus on enhanced multimodal fusion, self-supervised learning for improved generalization, and energy-efficient architectures for sustainable deployment. These innovations collectively strengthen the role of deep learning in building intelligent, responsive, and secure smart traffic management ecosystems.

VII. CHALLENGES

Environmental and Visibility Challenges – One of the major challenges in emergency vehicle recognition using Deep CNN is poor visibility caused by night-time conditions, heavy rain, fog, shadows, and glare from headlights. These environmental factors reduce image clarity and affect feature extraction, making it difficult for the model to accurately detect flashing lights or distinguish emergency vehicles from regular vehicles. Additionally, occlusion in dense traffic—where emergency vehicles are partially blocked by buses, trucks, or other cars—further complicates real-time detection.

Data and Model Limitations – Deep CNN models require large and well-balanced datasets for effective training, but emergency vehicle datasets are often limited and imbalanced compared to normal vehicle data. Variations in vehicle design, color patterns, siren light styles, and regional differences also impact model generalization. Overfitting, high computational requirements, and the need for continuous retraining to adapt to new vehicle models present further technical challenges in maintaining high detection accuracy.

Real-Time Deployment and System Integration – Implementing emergency vehicle recognition in real-world smart traffic systems demands low-latency processing and seamless integration with traffic signal controllers. High computational costs can slow inference speed, especially on edge devices. Moreover, false positives or missed detections can disrupt traffic flow or delay emergency response. Ensuring reliable communication between AI detection systems and adaptive traffic infrastructure remains a critical challenge for large-scale deployment.

VIII. CONCLUSION

The project successfully implements a real-time emergency vehicle recognition system using Deep Convolutional Neural Networks (CNNs). The system accurately detects and classifies ambulances, fire trucks, and police vehicles from live traffic video. The proposed approach supports smart traffic management by enabling priority movement for emergency vehicles. Experimental results show improved accuracy and faster response time even in complex traffic conditions. Overall, the system enhances emergency response efficiency, road safety, and intelligent transportation systems.

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